

Fusing High Resolution, Physically-Based Models and Remote Sensing to Understand and Predict Water Fluxes and Stocks

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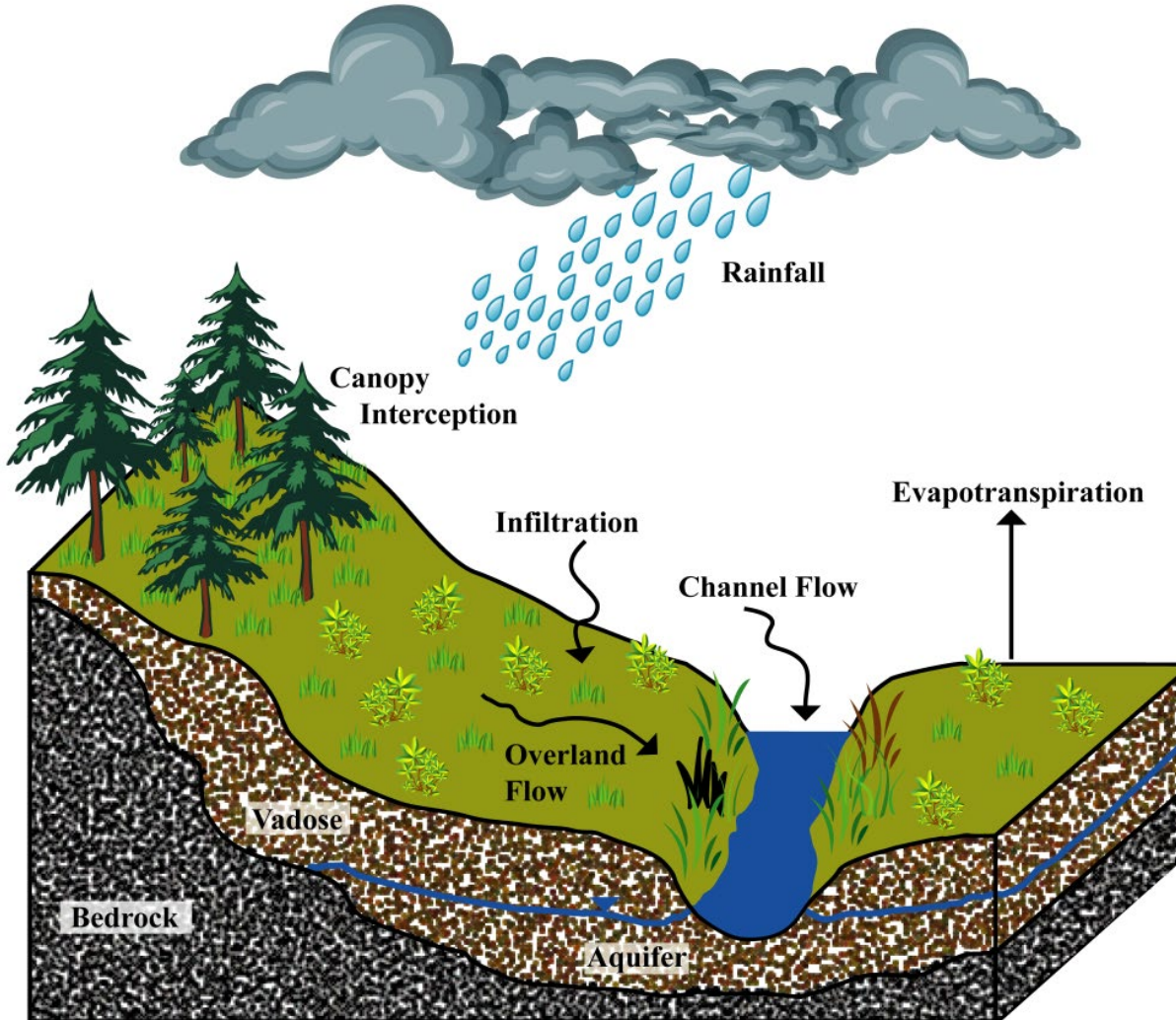


Outline

1. Improving hyper-resolution modeling for watershed predictions.
2. Hydrologic effects of forest disturbance
3. Real-time river flood forecasting
4. Soil moisture and ET processes
5. Bathymetry and surface water storage using smart sampling systems

tRIBS:

Tin-based Real-time Integrated Basin Simulator



- Need for process-based modeling constantly remarked in journal opinion papers.
- Distributed and continuous.
- Topography, land cover and soils types.
- Coupled vadose and saturated zones.
- Runoff mechanisms and channel routing.
- Water and energy balance.
- Snow processes

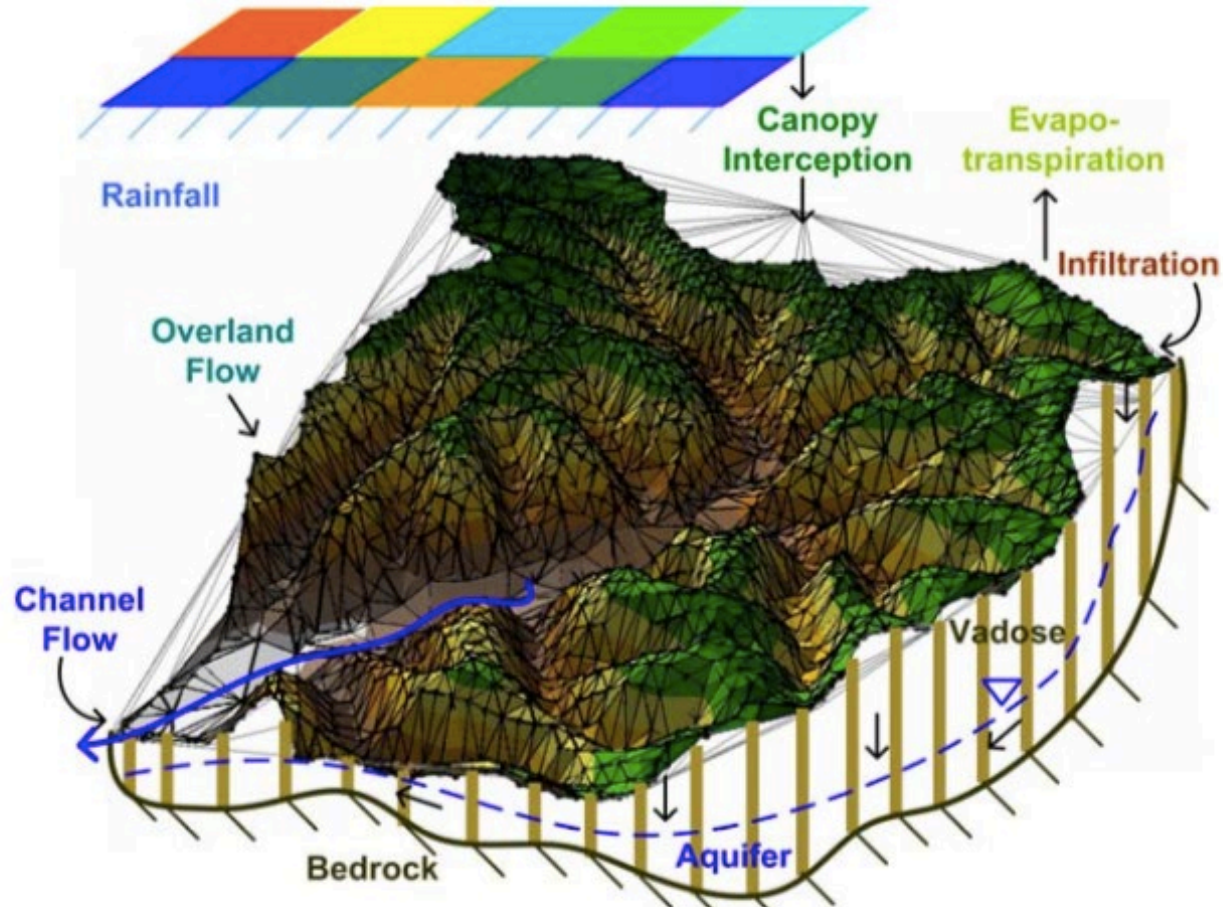


Table II. Hydrologic components of the tRIBS distributed hydrologic model

Model process	Description
Rainfall interception	Canopy water balance model
Surface energy balance	Combination equation (λE), gradient method (H) and force-restore equation (G)
Surface radiation model	Short-wave and long-wave components accounting for terrain variability
Evapotranspiration	Bare soil evaporation, transpiration and evaporation from wet canopy
Infiltration	Kinematic approximation with capillarity effects; unsaturated, saturated and perched conditions; top and wetting infiltration fronts
Lateral vadose flow	Topography-driven lateral unsaturated and saturated vadose flow
Runoff production	Infiltration-excess, saturation-excess, perched return flow and groundwater exfiltration
Groundwater flow	Two-dimensional flow in multiple directions, dynamic water table
Overland flow	Nonlinear hydrologic routing
Channel flow	Kinematic wave hydraulic routing

What are the spatially distributed hydrologic effects of forest thinning?

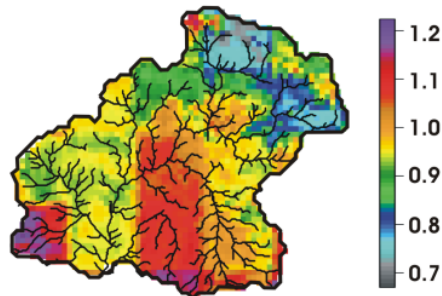
Reference case

Projected Change

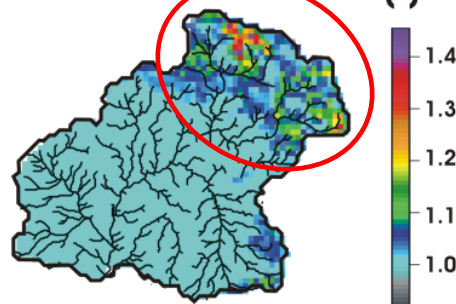
Reference case

Projected Change

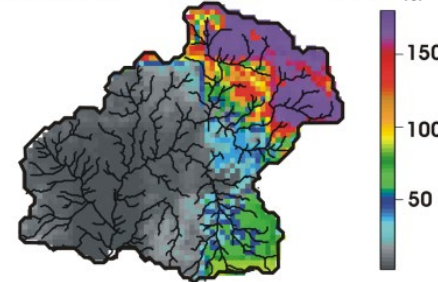
Average Runoff Rate, R_{ref} (mm/h)



R_v/R_{ref}



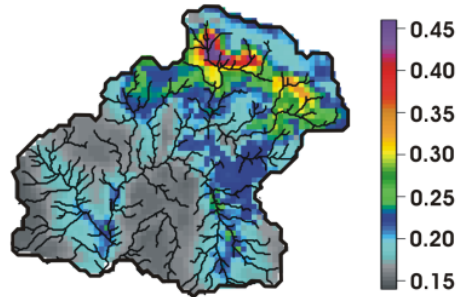
Longest Number of Days of Continuous Snow Cover, NDS_{ref}



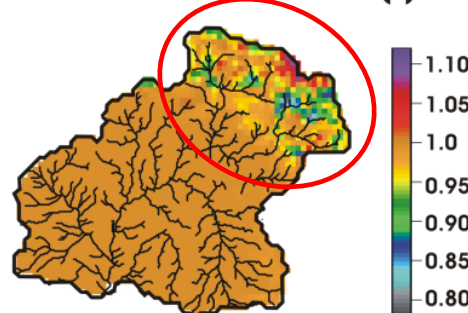
$NDS_v - NDS_{ref}$ (days)



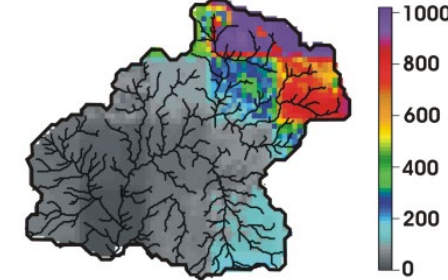
Vadose Zone Soil Moisture, θ_{ref} (-)



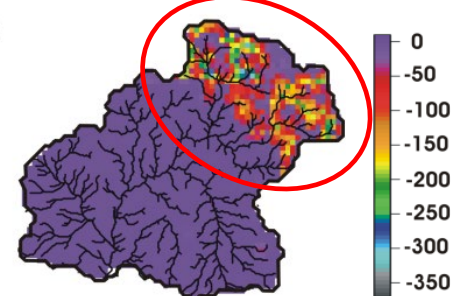
θ_v/θ_{ref}



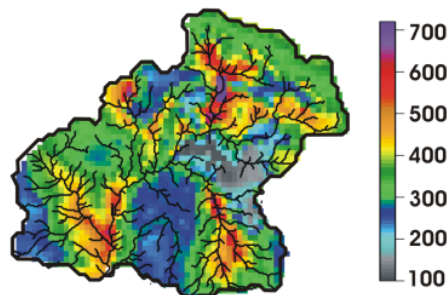
Maximum Season SW, $SW_{max,ref}$ (mm)



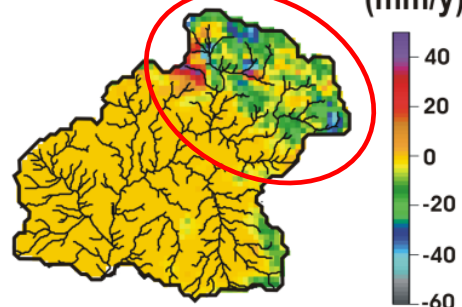
$SW_{max,v} - SW_{max,ref}$ (mm)



Evapotranspiration, ET_{ref} (mm/y)



$ET_v - ET_{ref}$



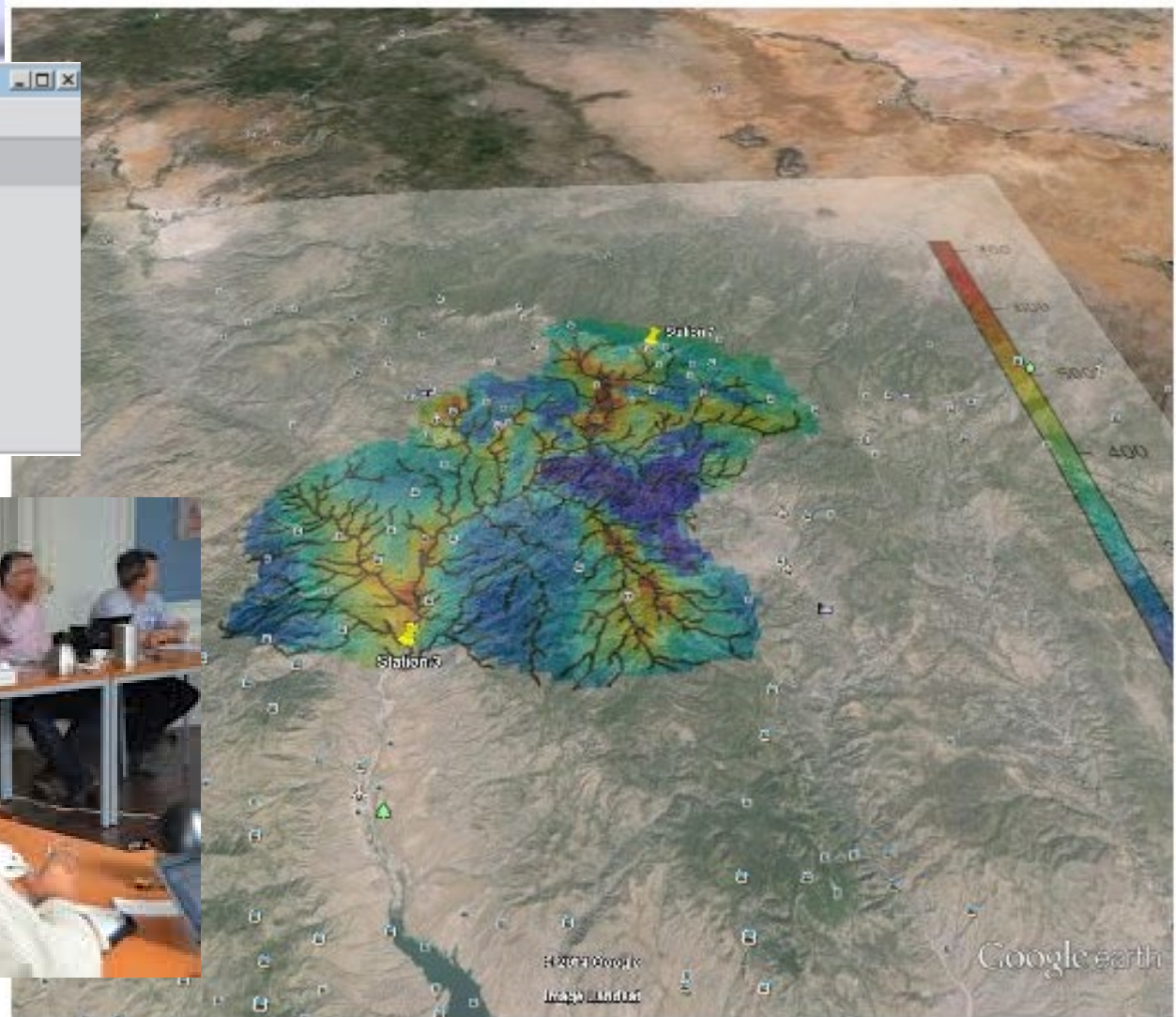
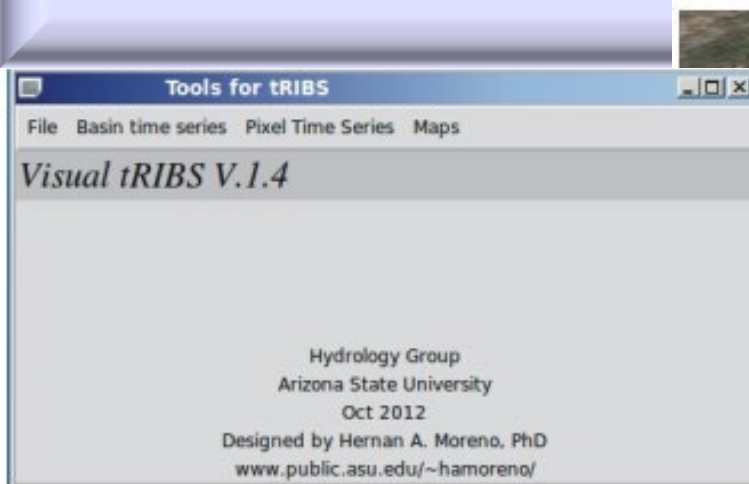
Local runoff increases

Soil moisture and ET mixed patterns

Days with snow cover reduced between 1 and 60 days

Max. snow water reduced in 350 mm

Participatory modeling for water security

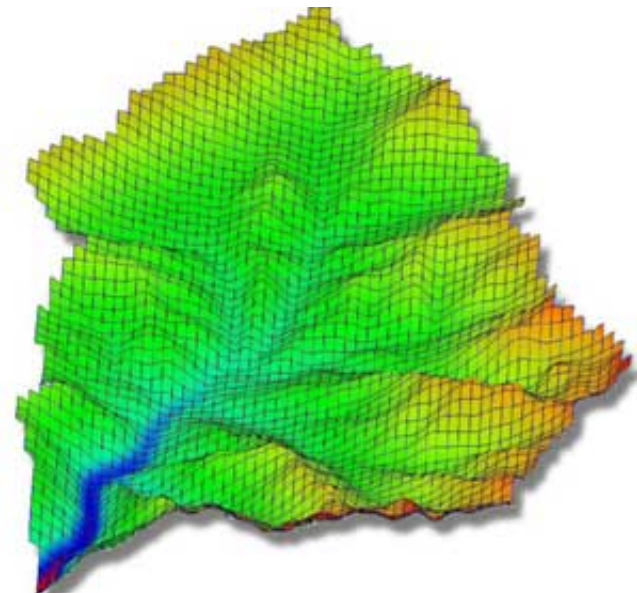
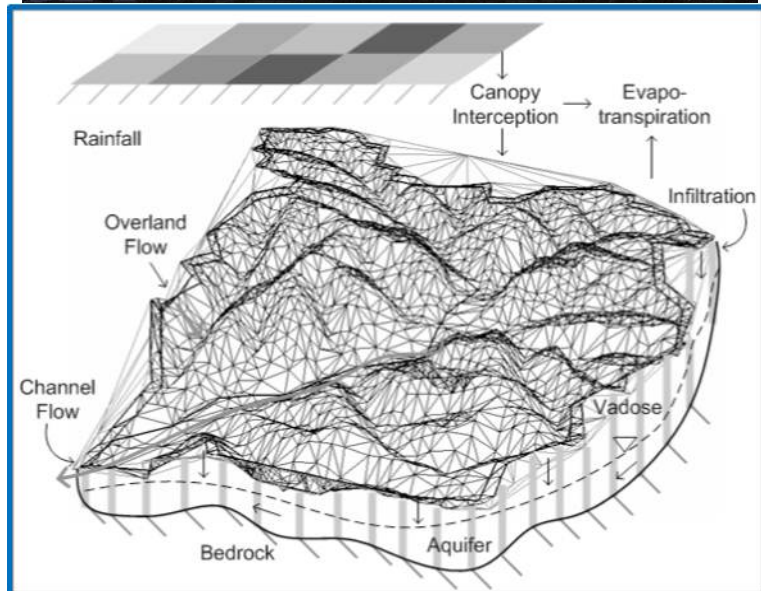
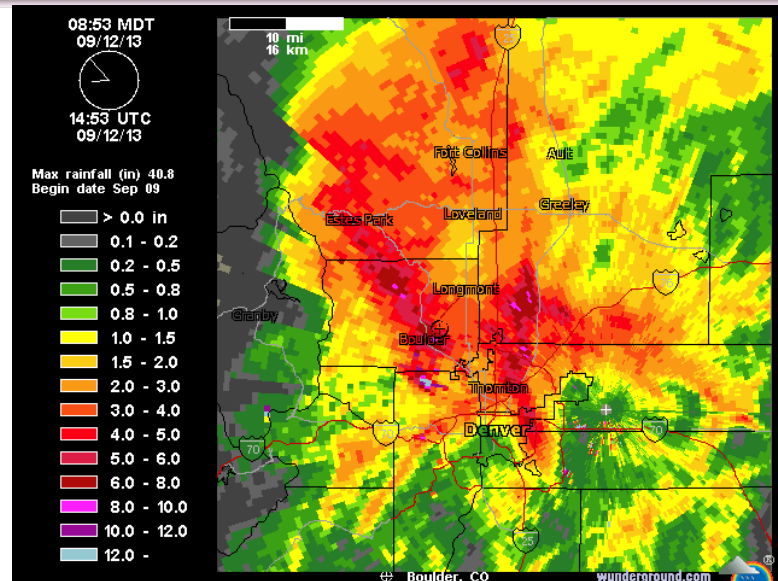
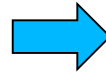
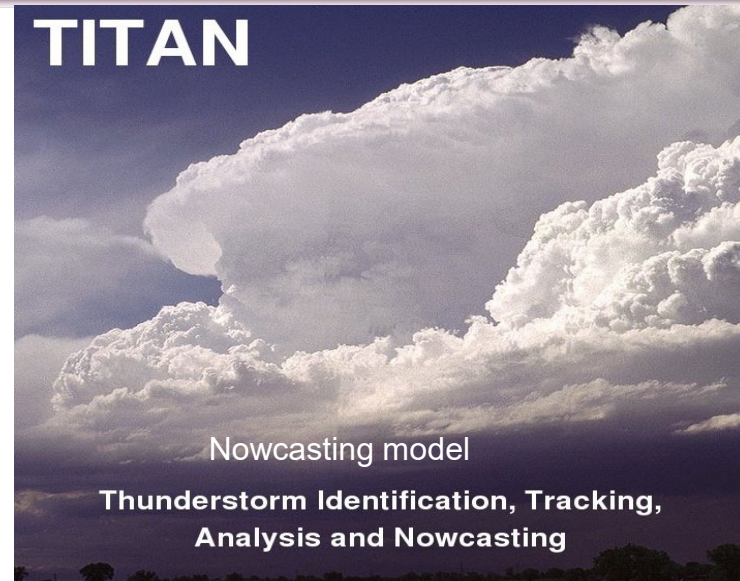


Google earth

miles 20
km 40



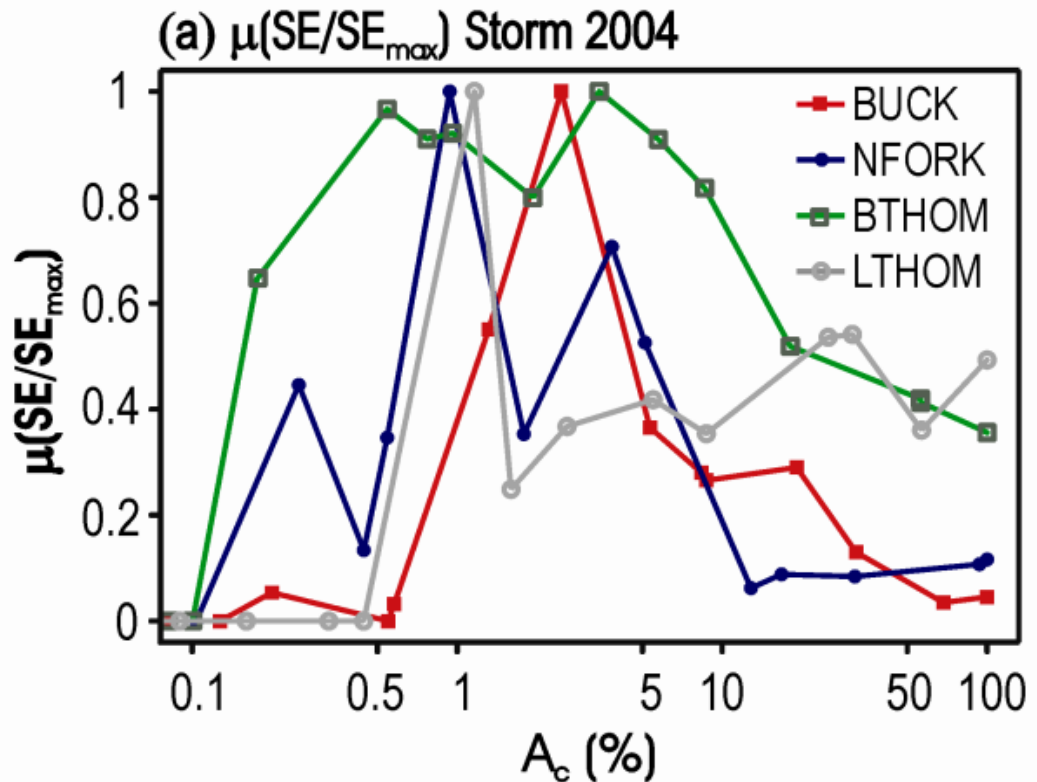
Radar nowcasts + tRIBS



What basin sizes are more predictable?

Standard Error

$$SE = \frac{Q_R}{A_c M A}$$



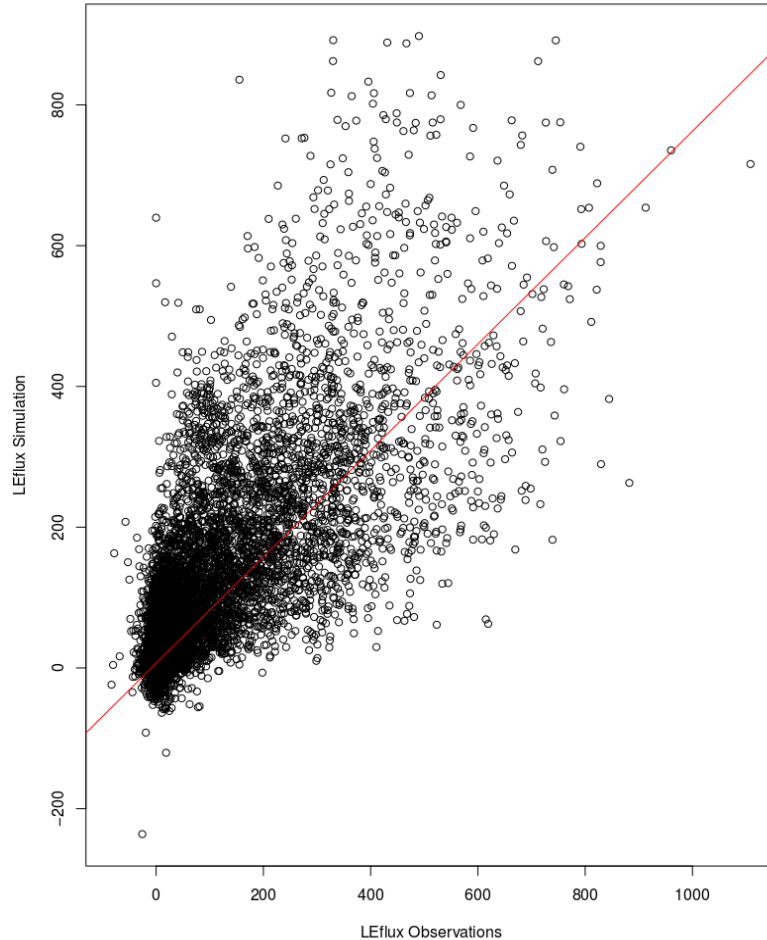
Floods less predictable at Intermediate size basins (1-10% of total Area) as a result of an increased fraction of runoff producing zones.

Virtual Mesonet Eddy-Covariance



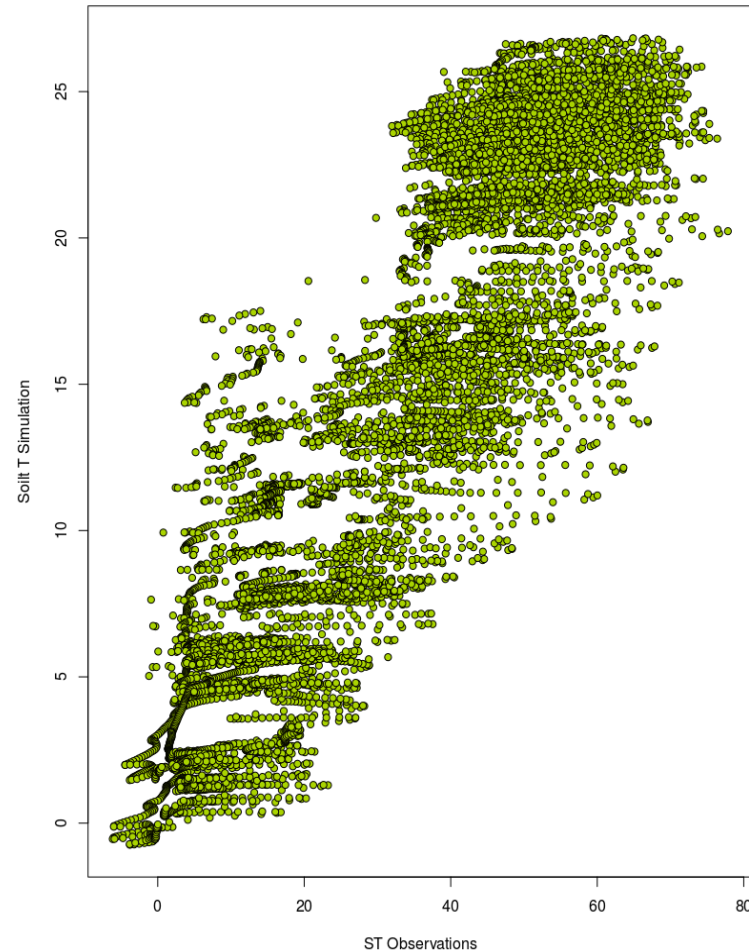
Preliminary simulations at one eddy station

Plot of Simulations Vs Observations



Latent heat flux

Plot of Simulations Vs Observations

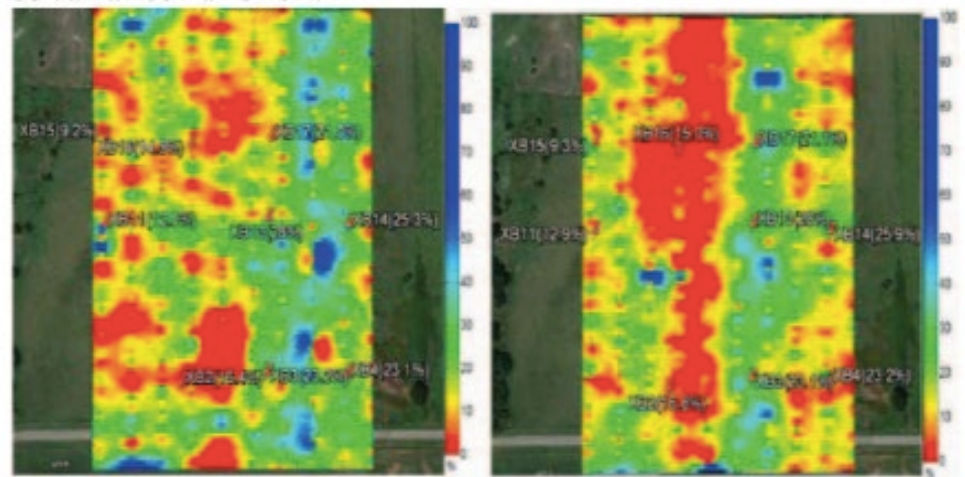


Soil surface temperature

Fusing L-band radiometers and observations to improve continuous and accurate modeling



Figure 4. Tempest UAS illustrating location of LDCR and MiCo antenna elements.



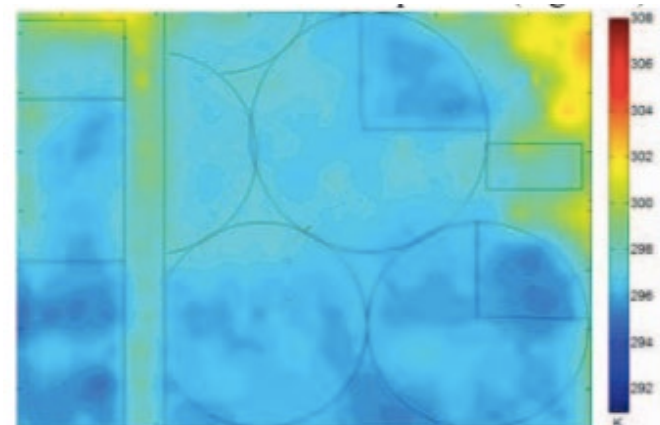
(a)

(b)

Figure 5: Google earth images overlay of LDCR retrieved VSM maps and in-situ measured VSM, data from (a) September 8th, (b) September 9th.



Figure 7: Land cover classification of IRF mapping area.



(a)

Lake and river bathymetry from UAS



A.



B.

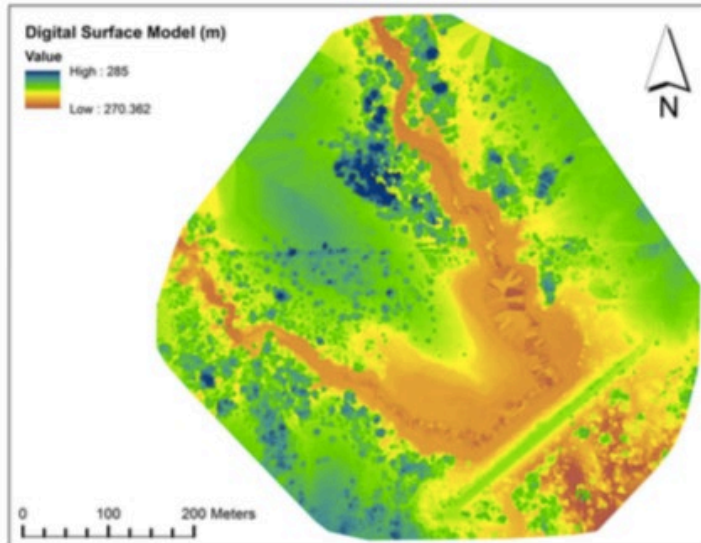


Figure 3. Pix4D software outputs: Orthomosaic and corresponding Digital Elevation Model (DEM)

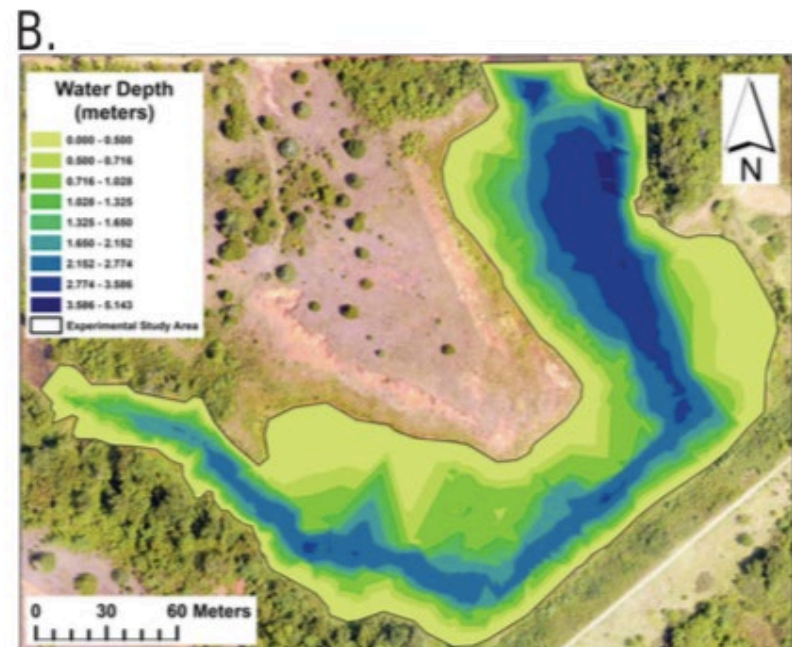


Figure 6. Bathymetry of Finn Creek 21 Reservoir using the single-beam echosounder. (a) Cumulative sampling points taken with the single-beam echosounder during August of 2017. (b) Bathymetric mapping built with the single-beam echosounder is shown.

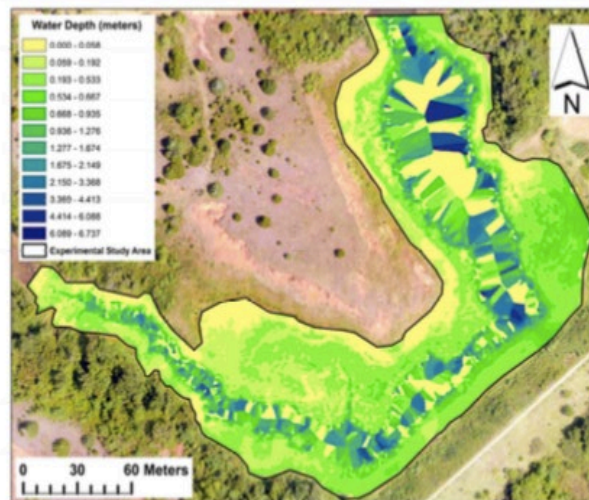


Figure 8. Bathymetry of Finn Creek 21 Reservoir using UAS-SfM technique taken during August of 2017.